

Coordinate and Coordinate Component Transformations

Rectangular to Cylindrical

$$\begin{aligned}x &= \rho \cos\phi \\y &= \rho \sin\phi \\z &= z \\&\quad \phi = \tan^{-1} \frac{y}{x} \\&\quad \rho = \sqrt{x^2 + y^2} \\&\quad z = z\end{aligned}$$

Cylindrical to Rectangular

$$\begin{aligned}r &= \sqrt{x^2 + y^2 + z^2} \\&\quad \theta = \tan^{-1} \frac{\sqrt{x^2 + y^2}}{z} \\&\quad \phi = \tan^{-1} \frac{y}{x} \\&\quad \rho = \sqrt{x^2 + y^2}\end{aligned}$$

Spherical to Rectangular

$$\begin{aligned}\begin{bmatrix}A_p \\ A_\phi \\ A_z\end{bmatrix} &= \begin{bmatrix}\cos\phi & \sin\phi & 0 \\ -\sin\phi & \cos\phi & 0 \\ 0 & 0 & 1\end{bmatrix} \begin{bmatrix}A_x \\ A_y \\ A_z\end{bmatrix} \\ \begin{bmatrix}A_x \\ A_y \\ A_z\end{bmatrix} &= \begin{bmatrix}\frac{x}{\sqrt{x^2 + y^2}} & -\frac{y}{\sqrt{x^2 + y^2}} & 0 \\ \frac{y}{\sqrt{x^2 + y^2}} & \frac{x}{\sqrt{x^2 + y^2}} & 0 \\ 0 & 0 & 1\end{bmatrix} \begin{bmatrix}A_p \\ A_\phi \\ A_z\end{bmatrix} \\ \begin{bmatrix}A_x \\ A_y \\ A_z\end{bmatrix} &= \begin{bmatrix}\frac{x}{\sqrt{x^2 + y^2 + z^2}} & \frac{yz}{\sqrt{x^2 + y^2 + z^2}} & -\frac{y}{\sqrt{x^2 + y^2}} \\ \frac{y}{\sqrt{x^2 + y^2 + z^2}} & \frac{zx}{\sqrt{x^2 + y^2 + z^2}} & \frac{x}{\sqrt{x^2 + y^2}} \\ \frac{z}{\sqrt{x^2 + y^2 + z^2}} & -\frac{xy}{\sqrt{x^2 + y^2 + z^2}} & 0\end{bmatrix} \begin{bmatrix}A_r \\ A_\theta \\ A_\phi\end{bmatrix}\end{aligned}$$

Rectangular to Spherical

$$\begin{aligned}x &= r \sin\theta \cos\phi \\y &= r \sin\theta \sin\phi \\z &= r \cos\theta\end{aligned}$$

Cylindrical to Spherical

$$\begin{aligned}\rho &= r \sin\theta \\&\quad \phi = \phi \\z &= r \cos\theta\end{aligned}$$

Spherical to Cylindrical

$$\begin{aligned}r &= \sqrt{\rho^2 + z^2} \\&\quad \theta = \tan^{-1} \frac{\rho}{z} \\&\quad \phi = \phi\end{aligned}$$

$$\begin{bmatrix}A_r \\ A_\theta \\ A_\phi\end{bmatrix} = \begin{bmatrix}\sin\theta \cos\phi & \sin\theta \sin\phi & \cos\theta \\ \cos\theta \cos\phi & \cos\theta \sin\phi & -\sin\theta \\ -\sin\phi & \cos\phi & 0\end{bmatrix} \begin{bmatrix}A_x \\ A_y \\ A_z\end{bmatrix}$$

$$\begin{aligned}\begin{bmatrix}A_r \\ A_\theta \\ A_\phi\end{bmatrix} &= \begin{bmatrix}\sin\theta & 0 & \cos\theta \\ \cos\theta & 0 & -\sin\theta \\ 0 & 1 & 0\end{bmatrix} \begin{bmatrix}A_p \\ A_\phi \\ A_z\end{bmatrix} \\ \begin{bmatrix}A_p \\ A_\phi \\ A_z\end{bmatrix} &= \begin{bmatrix}\frac{p}{\sqrt{p^2 + z^2}} & \frac{z}{\sqrt{p^2 + z^2}} & 0 \\ 0 & 0 & 1 \\ \frac{z}{\sqrt{p^2 + z^2}} & -\frac{p}{\sqrt{p^2 + z^2}} & 0\end{bmatrix} \begin{bmatrix}A_r \\ A_\theta \\ A_\phi\end{bmatrix}\end{aligned}$$